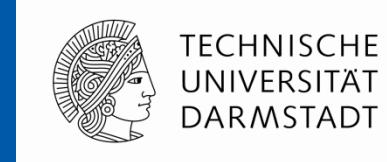


Incremental Model-Checking of Delta-oriented Software Product Lines



FOSD Meeting 2015



ES Real-Time Systems Lab

Prof. Dr. rer. nat. Andy Schürr

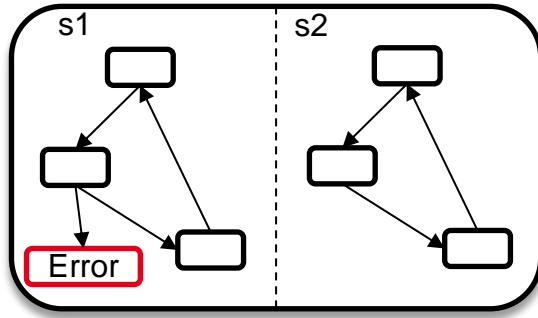
Dept. of Electrical Engineering and Information Technology

Dept. of Computer Science (adjunct Professor)

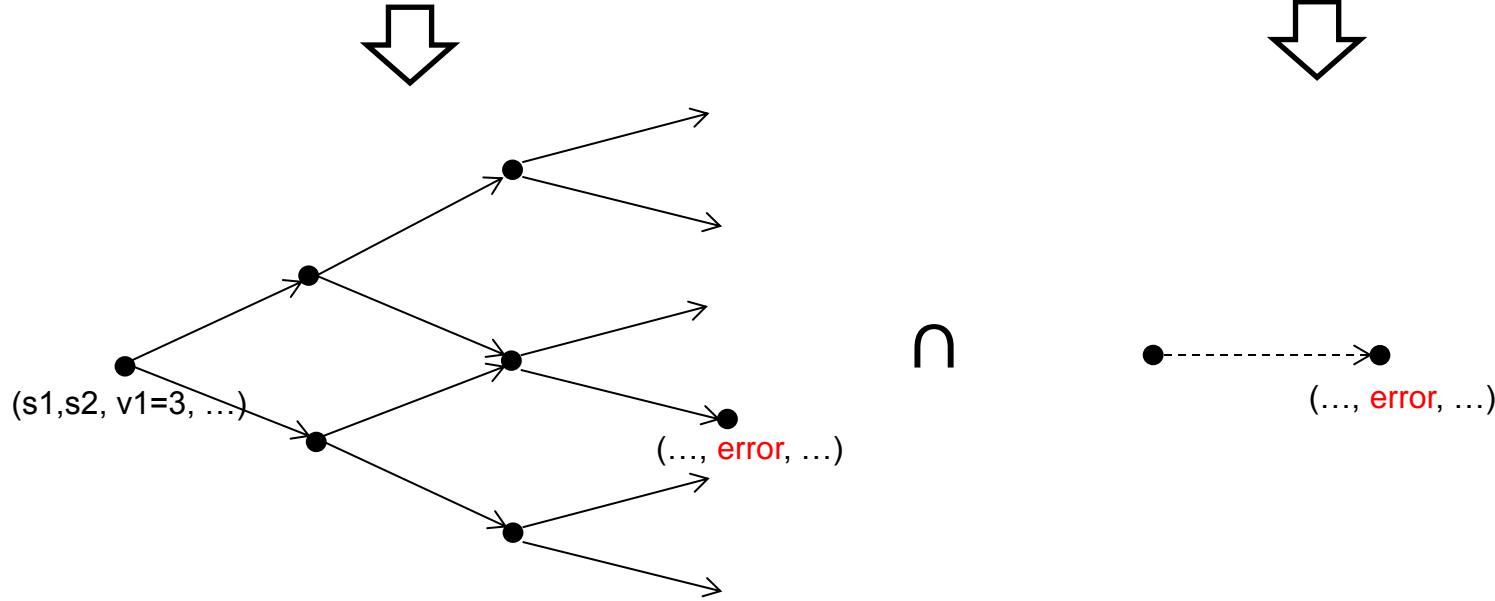
Malte Lochau, Stephan Mennicke, Hauke Baller

www.es.tu-darmstadt.de

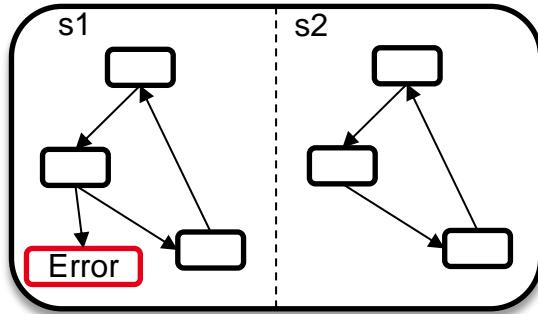
Model-Checking



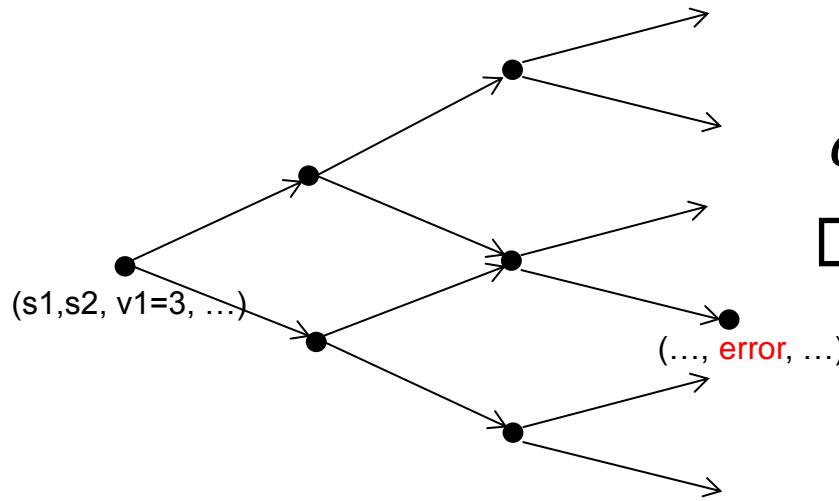
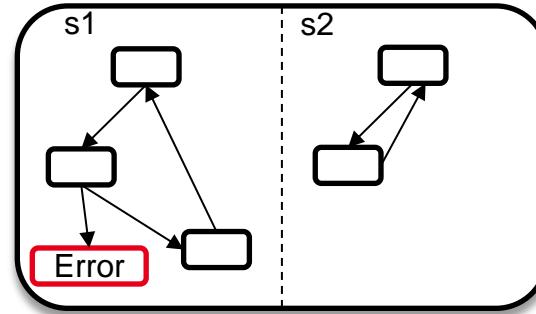
$\models AG(\neg Error)$



Syntactical vs. Semantical Changes



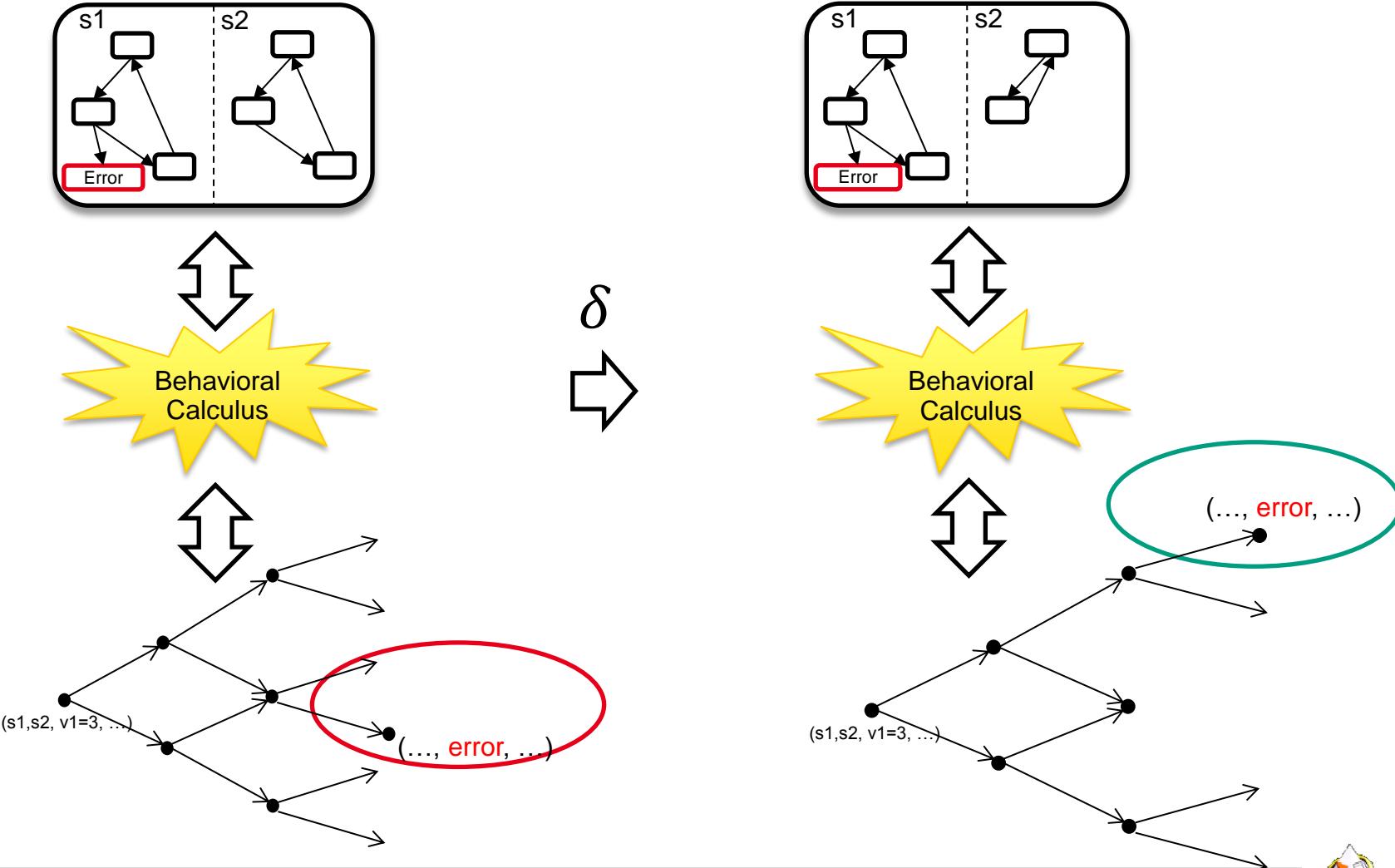
δ



δ



Semantical Models



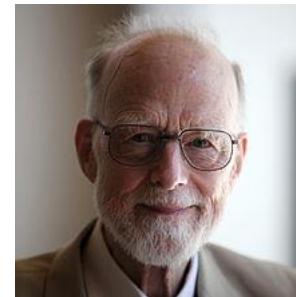
A Short History of Behavioral Core Calculi



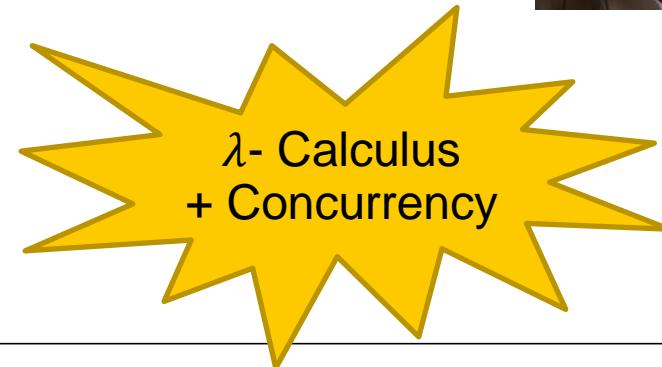
λ -Calculus
(1930)



CCS
(~1980)



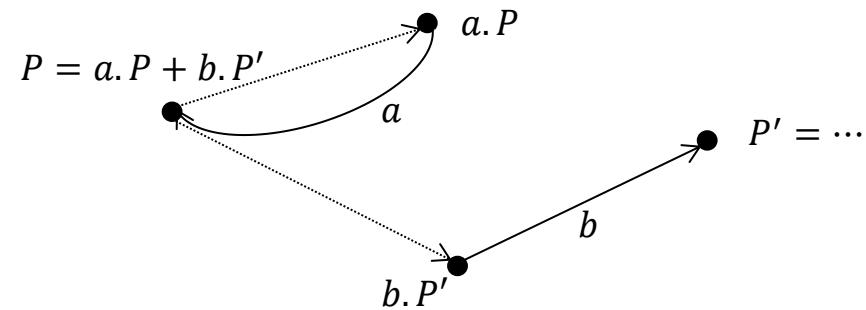
CSP
(~1978)



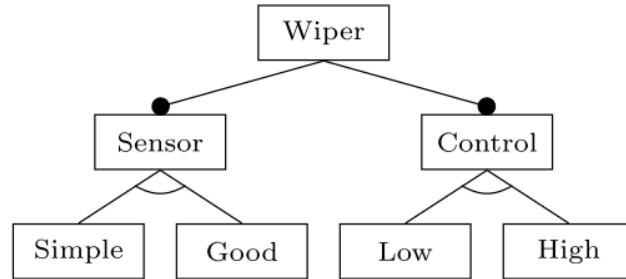
- CCS Syntax $P ::= \alpha.P \mid \sum_{i \in I} P_i \mid P \mid P \mid P[f] \mid P \setminus L \mid X$

- CCS Structural Operational Semantics

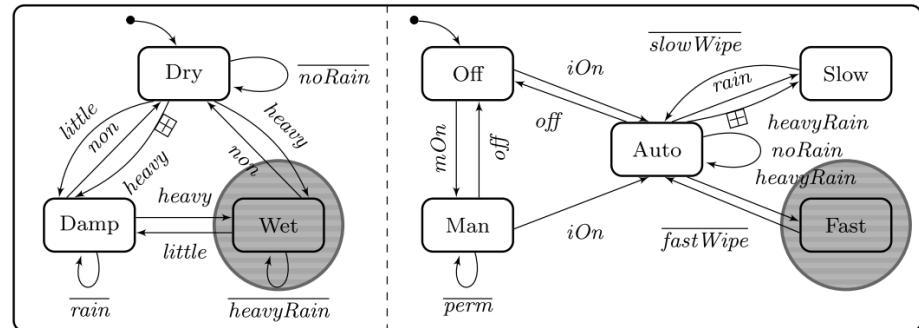
$$\begin{array}{c}
 (\text{pre}) \frac{}{\alpha.P \xrightarrow{\alpha} P} \quad (\text{rec}) \frac{P \xrightarrow{\alpha} P' \quad K \stackrel{\text{Def}}{=} P}{K \xrightarrow{\alpha} P'} \quad (\text{choice}) \frac{P_j \xrightarrow{\alpha} P'_j \quad j \in I}{\sum_{i \in I} P_i \xrightarrow{\alpha} P'_j} \\
 \\
 (\text{par-1}) \frac{P \xrightarrow{\alpha} P'}{P \mid Q \xrightarrow{\alpha} P' \mid Q} \quad (\text{par-2}) \frac{Q \xrightarrow{\alpha} Q'}{P \mid Q \xrightarrow{\alpha} P \mid Q'} \quad (\text{comm}) \frac{P \xrightarrow{\alpha} P' \quad Q \xrightarrow{\bar{\alpha}} Q'}{P \mid Q \xrightarrow{\tau} P' \mid Q'} \\
 \\
 (\text{rel}) \frac{P \xrightarrow{\alpha} P'}{P[f] \xrightarrow{f(\alpha)} P'[f]} \quad (\text{hide}) \frac{P \xrightarrow{\alpha} P' \quad \alpha, \bar{\alpha} \notin L}{P \setminus L \xrightarrow{\alpha} P' \setminus L}
 \end{array}$$



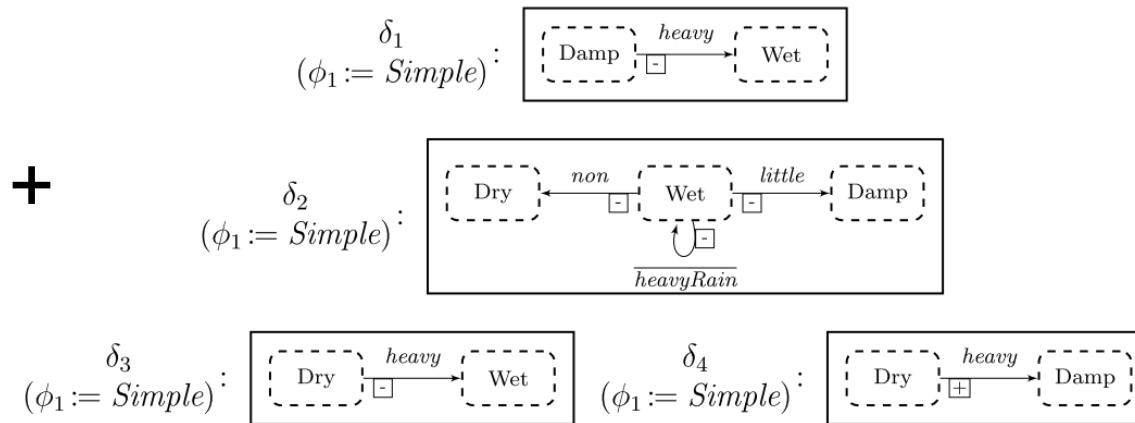
Delta-oriented Software Product Lines



Feature Model

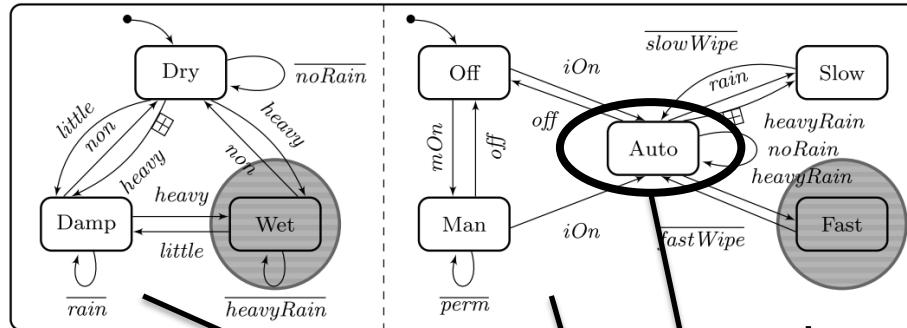


Core Product
(Good Sensor, High Control)



Deltas
(Good Sensor => Simple Sensor)

Translation of State Machines into CCS

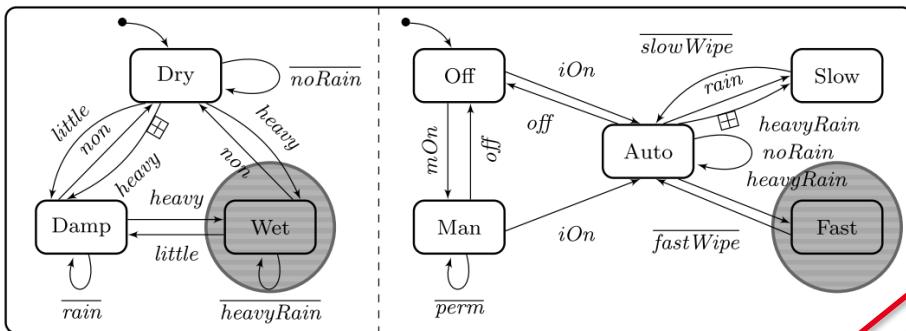


Initial process for root state
with sub machines

parallel sub processes
for sub machines

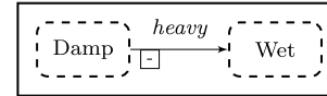
one process constant per state with
choice over outgoing transitions

$$\begin{aligned}
 P_c &= \text{Dry} \mid \text{Off} \\
 \text{Dry} &\stackrel{\text{Def}}{=} \overline{\text{noRain}}.\text{Dry} + \text{little}.\text{Damp} + \text{heavy}.\text{Wet} \\
 \text{Damp} &\stackrel{\text{Def}}{=} \text{rain}.\text{Damp} + \text{heavy}.\text{Wet} + \text{non}.\text{Dry} \\
 \text{Wet} &\stackrel{\text{Def}}{=} \text{heavyRain}.\text{Wet} + \text{little}.\text{Damp} + \text{non}.\text{Dry} \\
 \text{Off} &\stackrel{\text{Def}}{=} \text{mOn}.\text{Man} + \text{iOn}.\text{Auto} \\
 \text{Man} &\stackrel{\text{Def}}{=} \overline{\text{perm}}.\text{Man} + \text{off}.\text{Off} + \text{iOn}.\text{Auto} \\
 \text{Auto} &\stackrel{\text{Def}}{=} \text{noRain}.\text{Auto} + \text{rain}.\text{Slow} + \text{heavyRain}.\text{Fast} \\
 \text{Slow} &\stackrel{\text{Def}}{=} \text{slowWipe}.\text{Auto} \\
 \text{Fast} &\stackrel{\text{Def}}{=} \text{fastWipe}.\text{Auto}
 \end{aligned}$$

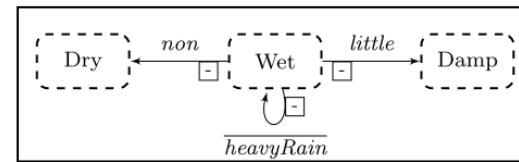


change transitions of state

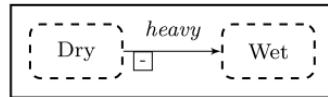
δ_1
 $(\phi_1 := \text{Simple})$:



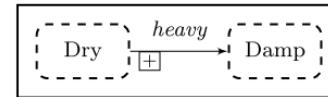
δ_2
 $(\phi_1 := \text{Simple})$:



δ_3
 $(\phi_1 := \text{Simple})$:



δ_4
 $(\phi_1 := \text{Simple})$:



$$\delta_1 = (\text{Damp}, \text{Simple}, \langle \text{Damp}' \stackrel{\text{Def}}{=} \overline{\text{rain}}.\text{Damp}' + \text{non}.\text{Dry} \rangle)$$

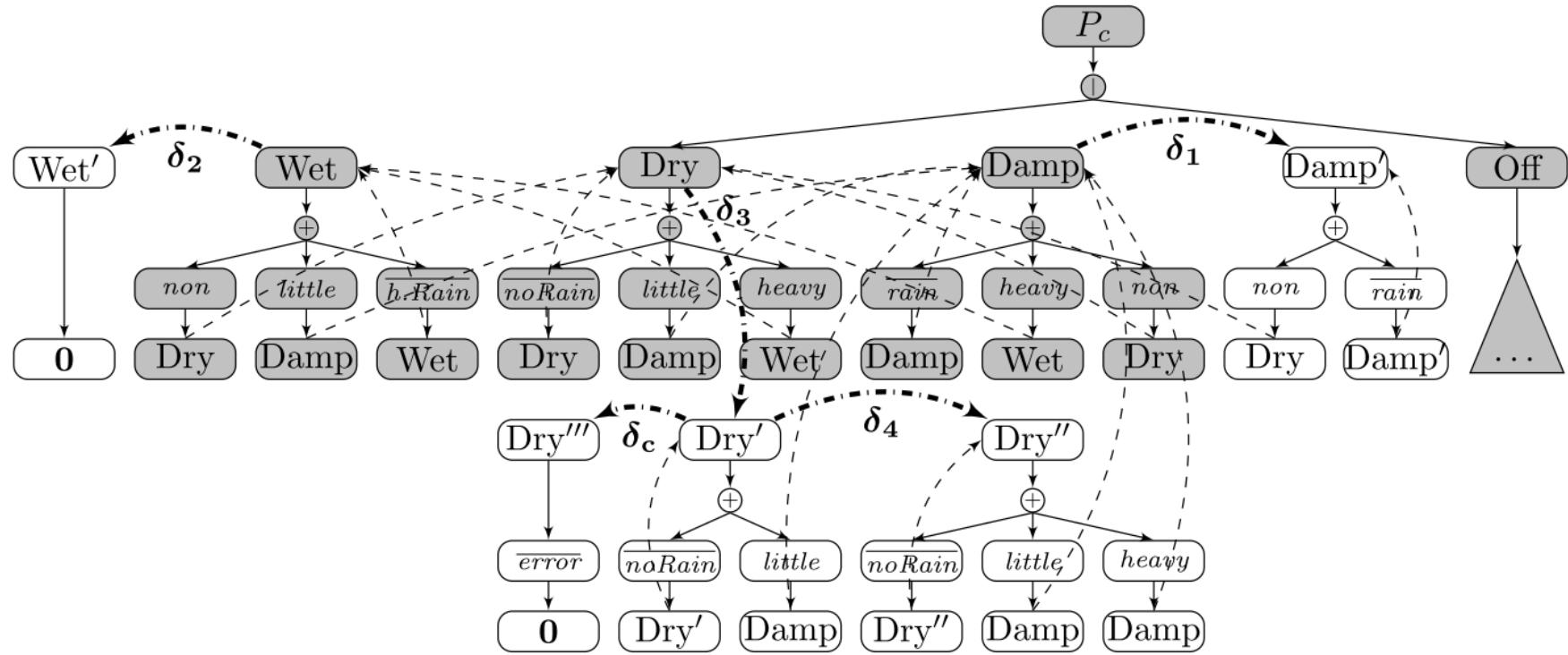
$$\delta_2 = (\text{Wet}, \text{Simple}, \langle \text{Wet}' \stackrel{\text{Def}}{=} \mathbf{0} \rangle)$$

$$\delta_3 = (\text{Dry}, \text{Simple}, \langle \text{Dry}' \stackrel{\text{Def}}{=} \overline{\text{noRain}}.\text{Dry}' + \text{little}.\text{Damp} \rangle)$$

$$\delta_4 = (\text{Dry}', \text{Simple}, \langle \text{Dry}'' \stackrel{\text{Def}}{=} \overline{\text{noRain}}.\text{Dry}'' + \text{little}.\text{Damp} + \text{heavy}.\text{Damp} \rangle)$$

change process constant def.
of state

Delta Dependency Graph



Formalizing the Notion of (Correct) Behavior



$$P \models \varphi$$

- What is φ ? temporal properties (safety, liveness)
- How to verify φ on CCS specifications P ? model checking
- What happens with φ in $\delta(P)$? it depends...

What is φ ?



Definition 4.1 (Modal μ -Calculus). A modal μ -calculus formula is an expression following the form $\nu Z.\psi \wedge [\alpha]Z$ or $\mu Z.\psi \vee \langle\alpha\rangle Z$ where

$$\psi ::= tt \mid ff \mid q \mid \neg q \mid Z \mid \psi \wedge \psi \mid \psi \vee \psi \mid \langle\alpha\rangle\psi \mid [\alpha]\psi$$

where $q \in \mathcal{P}$, $\alpha \in \text{Act}$ and $Z \in \text{Var}$. Let $P \in \mathcal{P}(\text{Act}, \mathcal{K})$ and φ a formula. Given an evaluation of atomic propositions $\mathcal{I}_{\mathcal{P}} : \mathcal{P} \rightarrow 2^{\mathcal{P}(\text{Act}, \mathcal{K})}$ and an evaluation of variables $\mathcal{I}_{\text{Var}} : \text{Var} \rightarrow 2^{\mathcal{P}(\text{Act}, \mathcal{K})}$, $P \models \varphi$ iff $P \in \|\varphi\|_{\mathcal{I}_{\text{Var}}}^{\mathcal{I}_{\mathcal{P}}}$ (cf. Fig. 6).

“[...] the system is intended to perform *fast wiping* whenever receiving the input *heavy*... [...]”:

$$\varphi := \mu Z.\langle\text{heavy}\rangle\langle\langle\overline{\text{fastWipe}}\rangle\rangle tt \vee \langle-\rangle Z$$

What happens with φ in $\delta(P)$? (1/4)

(1) $P \simeq P'$ iff P and P' satisfy the same set of μ -calculus formulae
[Stirling et al.]

(2) $P \equiv P'$ implies $P \simeq P'$

[Milner et al.]

➤ Standard Congruence on CCS Terms:

- $P + Q \equiv Q + P, P + P \equiv P, \dots$
- $P|Q \equiv Q|P, P|\mathbf{0} \equiv P$
- $\alpha.(P + Q) \not\equiv \alpha.P + \alpha.Q$
-

What happens with φ in $\delta(P)$? (2/4)



Proposition 4.1. Let $\delta = (K, \phi, K') \in \Delta(\mathcal{K}, \Phi)$ and $P, Q, P' \in \mathcal{P}(\text{Act}, \mathcal{K})$.

$$\delta(\alpha.P) \equiv \alpha.\delta(P) \quad (1)$$

$$\delta(P + Q) \equiv \delta(P) + \delta(Q) \quad (2)$$

$$\delta(P | Q) \equiv \delta(P) | Q \text{ if } \delta(Q) \equiv Q \quad (3)$$

$$\delta(X) \equiv \delta(P') \text{ if } K \neq X \text{ and } X \stackrel{\text{Def}}{=} P' \quad (4)$$

$$\delta(P) \equiv P \text{ if } \delta \text{ is not applicable in } P \quad (5)$$

What happens with φ in $\delta(P)$? (4/4)



Proposition 4.2. Let $P, Q, R \in \mathcal{P}(\text{Act}, \mathcal{K})$ and φ a μ -calculus formula.

$$P \models \varphi \wedge P \equiv Q \Rightarrow Q \models \varphi \quad (6)$$

$$P \models \varphi \wedge Q \models \varphi \Rightarrow P + Q \models \varphi \quad (7)$$

$$P | R \models \varphi \wedge P \equiv Q \Rightarrow Q | R \models \varphi \quad (8)$$

Theorem 4.1. Let $\delta = (K, \phi, K') \in \Delta(\mathcal{K}, \Phi)$ and $P \in \mathcal{P}(\text{Act}, \mathcal{K})$. If $\delta(P) \equiv P$ and $P \models \varphi$ then $\delta(P) \models \varphi$.

[M. Lochau, S. Mennicke, H. Baller, L. Ribbeck: DeltaCCS: A Core Calculus for Behavioral Change, 2014]

- Incremental SPL model-checker in MAUDE
- Define normal forms for (theoretically) optimal congruence application strategies
- Explore second DeltaCCS semantics for family-based SPL model checking
- Interleave family-based and incremental SPL Test Suite Generation